# University of Nottingham

## **Electromechanical devices MM2EMD**

## Lecture 3 - Digital design and race times

Dr. Roderick MacKenzie roderick.mackenzie@nottingham.ac.uk Summer 2015



Released under commons



## Recap of last lecture

- •Using JK flip flops to run motors
- Digital design
  What is digital design?
  How to do it.
  Where you might meat digital design
  FPGAs
- •Race times



- •If we have a circuit comprising of multiple gates we can analyze it by first writing out the truth table containing all possible input combinations.
- •With the output column left blank.



А	В	Q
0	0	
0	1	
1	0	
1	1	



•Then one line at a time, we propagate the values through the circuit.







Roderick MacKenzie





#### Then write the table in the output column.

Roderick MacKenzie



If we do this with all inputs we can figure out what the circuit does



А	В	Q
0	0	1
0	1	0
1	0	0
1	1	0

Roderick MacKenzie

# Recap: We did this with the more complex XOR gate circuit:





Roderick MacKenzie





•I introduced the principle of a latch.

•Latches are used to remember past electronic events.

•A latch always has some type of feed back element, here is an example....  $_{9}$ 





•If initially A, B and Q are zero

10 MM2EMD Electromechanical devices





- •If initially A, B and Q are zero
- Then you make input A=1





•This will make the output=1





•It will also make the input B, 1

13 MM2EMD Electromechanical devices





•Now if we again make input A 0

•No matter what we do the A the output will always remain 1 because of the feedback.

•The OR gate latch has remembered it was turned on due the the feedback – **it has latched**.



•However the problem with a latch is that the only way to turn it off is by breaking the feedback loop.



•We found that JK flip-flops are a more flexible latch which don't have this problem.

Roderick MacKenzie

Recap: We use a circuit called a JK flip-flop – it looks like this:

The University of Nottingham

•This is a real memory circuit that you would find in a computer. It can store a **1** or a **0**.



It looks a bit complicated.



## Recap: The JK flipflop





Roderick MacKenzie

MM2EMD Electromechanical devices

17



The value the flip flop is currently remembering appears on pin Q and the inverse appears on pin  $\overline{Q}$ .





•This is the most basic electronic memory element used to store 1's or 0's.

The University of

Nottingham

 It is therefore important to remember what it does and how you would use it.

•You will meet this all the time as soon as you start working with electronic circuits. Used in **memory**, **counters**, **processors** etc...



•The basic idea is that you put what you want to remember on the J input – in this case a 1.





•At the same time you put the inverse of what you want to store on the K input:







•You then change the CLK (clock) pin from a 0 to a 1.



## Recap: Storing a 1





Roderick MacKenzie

Recap: We need a clock pulse to remember things.



# •Then no matter what you do the **J** or K pins the **output will remain unchanged**



## Recap: Storing a zero





Roderick MacKenzie

## Recap: Storing a zero





MM2EMD Electromechanical devices

26

## Recap: Storing a zero





Roderick MacKenzie

Recap: Nothing happens without a clock pulse.

# •Then no matter what you do the **J** or K pins the **output will remain unchanged**



Roderick MacKenzie

MM2EMD Electromechanical devices

28





Roderick MacKenzie



## Recap of last lecture

## Using JK flip flops to run motors

# Digital design What is digital design? How to do it. Where you might meat digital design FPGAs

•Race times

## Switch reluctance (SR) motor



•An SR motor is a motor which has an iron bar at it's center.

The University of

Nottingham

•You can move the bar by turning on and off the field in the different electromagnets.

•It's like the stepper motor Arthur has been teaching you about but a bit more simple 31

## Green electromagnet on





32 MM2EMD Electromechanical devices

## Blue electromagnet on





33 MM2EMD Electromechanical devices

## Red electromagnet on





34 MM2EMD Electromechanical devices

## Green electromagnet on





35 MM2EMD Electromechanical devices

## Blue electromagnet on





36 MM2EMD Electromechanical devices
### Red electromagnet on





37 MM2EMD Electromechanical devices

#### Green electromagnet on





38 MM2EMD Electromechanical devices

### Blue electromagnet on





•By switching on and off the magnetic field you can move the motor.

•Good, but what has this got to do with digital electronics?

39 MM2EMD Electromechanical devices





32 wires

40 MM2EMD Electromechanical devices







41 MM2EMD Electromechanical devices





Clock

42 MM2EMD Electromechanical devices





Clock

43 MM2EMD Electromechanical devices





Clock

44 MM2EMD Electromechanical devices





Clock

45 MM2EMD Electromechanical devices





Clock

46 MM2EMD Electromechanical devices





Clock

47 MM2EMD Electromechanical devices





Clock

48 MM2EMD Electromechanical devices





Clock

49 MM2EMD Electromechanical devices





Clock

50 MM2EMD Electromechanical devices





Clock

51 MM2EMD Electromechanical devices





Clock

52 MM2EMD Electromechanical devices





Clock

53 MM2EMD Electromechanical devices

Are there any similarities between the Nottingham motor and the serial to parallel converter?





We can actually convert the serial to parallel converter circuit to a motor driver circuit.

Roderick MacKenzie

MM2EMD Electromechanical devices

54





#### Firstly let's only switch on one JK flipflop



# And get rid of one flipflop

MM2EMD Electromechanical devices





Clock

Let's connect the input to the output....

Roderick MacKenzie

MM2EMD Electromechanical devices





•And replace the bulbs with the coils of the motor....

Roderick MacKenzie

MM2EMD Electromechanical devices

# Replace the bulbs with the coils of the motor.



Roderick MacKenzie

MM2EMD Electromechanical devices

The University of

Nottingham

### And apply a clock pulse...





Roderick MacKenzie

MM2EMD Electromechanical devices

Now let's join the input to the output 🎾



Roderick MacKenzie

MM2EMD Electromechanical devices

The University of

Nottingham







#### •Now apply another clock pulse.

MM2EMD Electromechanical devices

The University of







### •Now apply another clock pulse.

MM2EMD Electromechanical devices

The University of





Roderick MacKenzie

**MM2EMD Electromechanical devices** 

The University of







### •Now apply another clock pulse.

MM2EMD Electromechanical devices







The University of





Roderick MacKenzie

MM2EMD Electromechanical devices







#### •Now apply another clock pulse.

MM2EMD Electromechanical devices

The University of



- •Recap of last lecture
- •Using JK flip flops to run motors

# Digital design

- •What is digital design?
- •How to do it.
- •Where you might meat digital design•FPGAs

•Race times



•In the first couple of lectures we learnt about:

AND gatesOR gatesNOT gatesXOR gates

•We also made some simple circuits involving AND gates and OR gates.

•However there are often times when you need to design much more complex circuits as an engineer.

# Examples of slightly complex digital circuits



 Imagine you were designing a circuit to monitor a digital thermometer embedded in a nuclear reactor.





# Examples of slightly complex digital circuits



•You wanted to automatically shut off the reactor when the cooling fluid (water) got higher than 50 degrees.



Rama



# Examples of slightly complex digital circuits

- •They did not have one of these circuits in Chernobyl...
- •Quite a useful type of circuit to learn about(!)





#### 72 MM2EMD Electromechanical devices

The University of

Nottingham

TT
The University of Nottingham

•Your digital thermometer gives it's output using a three digit binary number.



#### 73 MM2EMD Electromechanical devices

#### Roderick MacKenzie



•In normal numbers that is.....



74 MM2EMD Electromechanical devices

#### Roderick MacKenzie



•Each number corresponds to a 10 degree step in temperature...

	_	$O_1$	02	03	Number	remperature
°C 100	$O_1$	0	0	0	0	0
00 08 08		0	0	1	1	10
	$O_2$	0	1	0	2	20
		0	1	1	3	30
	$O_{3}$	1	0	0	4	40
		1	0	1	5	50
		1	1	0	6	60
		1	1	1	7	70

•We want to design a circuit that shuts off the reactor if the temperature is above 50 degrees.

The University of Nottingham

•We want to design a circuit that shuts off the reactor if the temperature is above 50 degrees.



If **S=1** the reactor will shutdown and if **S=0** the reactor will continue working.

Draw a truth table for the circuit we want to design



$O_1$	02	O <sub>3</sub>	Number	Temperature	S
0	0	0	0	0	0
0	0	1	1	10	0
0	1	0	2	20	0
0	1	1	3	30	0
1	0	0	4	40	0
1	0	1	5	50	0
1	1	0	6	60	1
1	1	1	7	70	1

•Remember

- •S=0 means stay on
- •S=1 shutdown

### Truth table



<b>O</b> <sub>1</sub>	O <sub>2</sub>	O <sub>3</sub>	Number	Temperature	S
0	0	0	0	0	0
0	0	1	1	10	0
0	1	0	2	20	0
0	1	1	3	30	0
1	0	0	4	40	0
1	0	1	5	50	0
1	1	0	6	60	1
1	1	1	7	70	1

•We need to construct two logic circuits that give a 1 when the inputs are 110 and 111.

•Let's look at the 111 case first because it's easy

Roderick MacKenzie

MM2EMD Electromechanical devices

•We want a circuit that will produce a 1 when all inputs are 1

•Let's just use an AND agate with three inputs.

D <sub>1</sub> <b>O</b>	
ی <b>و</b>	

$O_1$	O <sub>2</sub>	O <sub>3</sub>	S
0	0	0	0
0	0	1	0
0	1	0	0
0	1	1	0
1	0	0	0
1	0	1	0
1	1	0	0
1	1	1	1



# Now let's make a circuit for the 60 degree case



01	O <sub>2</sub>	O <sub>3</sub>	Number	Temperature	S
0	0	0	0	0	0
0	0	1	1	10	0
0	1	0	2	20	0
0	1	1	3	30	0
1	0	0	4	40	0
1	0	1	5	50	0
1	1	0	6	60	1
1	1	1	7	70	1

•We want a circuit that will produce a 1 when all inputs are 1 except  $O_3$ .

Roderick MacKenzie

80 MM2EMD Electromechanical devices



•We want a circuit that will produce a 1 when all inputs are 1 except  $O_{3}$ .

•Let's just make an and gate with input  $O_3$  inverted.



	$O_1$	O <sub>2</sub>	0	S
			3	
	0	0	0	0
	0	0	1	0
	0	1	0	0
	0	1	1	0
	1	0	0	0
	1	0	1	0
	1	1	0	1
MM2F	1	1	1	0

Roderick MacKenzie

### One more example

 Presumably it would also be bad if our coolant froze so let's make a circuit to shut down the reactor if the temperature is freezing



$O_{1}$	0 <sub>2</sub>	O <sub>3</sub>	Number	Temperature	S	
0	0	0	0	0		
0	0	1	1	10	0	
0	1	0	2	20	0	
0	1	1	3	30	0	
1	0	0	4	40	0	منحر
1	0	1	5	50	0	rlzar
1	1	0	6	60	1	Ň
1	1	1	7	70	1	I.

82 MM2EMD Electromechanical devices

The University of

Nottingham



•So now we want our circuit to produce a 1 when O1, O2 and O3 are all set to 0.

So let's just invert all the inputs. So the AND gate only turns on when all inputs are 0.



O <sub>1</sub>	O <sub>2</sub>	0	S
		3	
0	0	0	1
0	0	1	0
0	1	0	0
0	1	1	0
1	0	0	0
1	0	1	0
1	1	0	1
1	1	1	0

MM2E





•We now have three circuits which all give one when our criteria to shut down the reactor are met.



### Join together the inputs



The University of

Nottingham

### Join together the inputs





## Join together the inputs



•This circuit will produce this truth table.



The University of

Nottingham

•Finished!!! 87

The University of Nottingham

•And we have correctly interfaced our thermometer to the nuclear power plant shut down circuit.



•And our nuclear power plant can no longer blow up!

**Roderick MacKenzie** 

MM2EMD Electromechanical devices

## Recap – how to design digital circuits 1



#### •Write out the truth table

<b>O</b> <sub>1</sub>	O <sub>2</sub>	0	S
		3	
0	0	0	1
0	0	1	0
0	1	0	0
0	1	1	0
1	0	0	0
1	0	1	0
1	1	0	1
1	1	1	1

Roderick MacKenzie

89 MM2EMD Electromechanical devices •Use AND and NOT gates that produce circuits that only give a 1 when a set of desired inputs is met





•Stitch the inputs together and join the outputs with an OR gate.



#### •And that is it! 91



•You can now design any digital circuit that is thrown at you if you follow those simple steps.

 You can now even design the circuits that go into computer chips using this method



#### Roderick MacKenzie

## Adding unit





#### 93 MM2EMD Electromechanical devices

#### Roderick MacKenzie



•However that's a bit complex to do in the lecture. So you will now design a circuit to detect if a number is odd:

•Hint you need four AND gates, one OR gate, and a collection of NOT gates.

O <sub>1</sub>	O <sub>2</sub>	O <sub>3</sub>	S
0	0	0	0
0	0	1	1
0	1	0	0
0	1	1	1
1	0	0	0
1	0	1	1
1	1	0	0
1	1	1	1

#### The answer





Roderick MacKenzie

MM2EMD Electromechanical devices





#### •Do you notice something about this truth table??

	Value	O <sub>1</sub>	02	O <sub>3</sub>	S	
	0	0	0	0	0	
	1	0	0	1	1	
	2	0	1	0	0	
	3	0	1	1	1	
	4	1	0	0	0	
	5	1	0	1	1	
	6	1	1	0	0	
•When ever	7 O <sub>3</sub> is (	1 one w	<mark>1</mark> /e ha	<mark>1</mark> ave a	1 n od	d number

**Roderick MacKenzie** 

MM2EMD Electromechanical devices



•We could actually replace this whole circuit with a wire!! (in this case):



•The method I have just taught you will work 100% of the time without any problems.

•However, it will not try to simplify the circuit at all and you may end up using far more gates than you really need.

## A much simpler circuit



•There are programs which will take a truth table and convert in into a minimized circuit which uses the least number of gates that are possible.

🖌 Truth Table							
Dec	Hex	A	В	C	D	F1	
0	0	0	0	0	0		
1	1	0	0	0	1		
2	2	0	0	1	0		
3	3	0	0	1	1		
4	4	0	1	0	0	1	
5	5	0	1	0	1		
6	6	0	1	1	0		
7	7	0	1	1	1		
8	8	1	0	0	0	1	
9	9	1	0	0	1		
10	A	1	0	1	0		
11	В	1	0	1	1		
12	С	1	1	0	0	1	
13	D	1	1	0	1		
14	Е	1	1	1	0		
15	F	1	1	1	1		



•If you start doing this seriously in industry I suggest you take a look at some of this software..

## Field programmable gate array



•Final tip, I have introduced you to logic chips that look like this, they have contain 8 gates.





•Although these chips are still used (especially in glue logic).

•It is very common today to use something called an (Field programmable gate array) FPGA.

•This single chip can contain half a million gates and the connections between each gate are programmable.

•This means you can actually 'rewire' your circuit with a computer while your machine is running.

•You will meet theses in industry. Roderick MacKenzie



Cost <10 pounds 100 MM2EMD Electromechanical devices

## Last tip on digital electrons **race times**

•Think about this circuit, if you changed the inputs from 11 to 00 the outputs would not change.





The University of

Nottingham

## •Let's draw this out in detail

101 MM2EMD Electromechanical devices

#### Roderick MacKenzie

102 MM2EMD Electromechanical devices

### Last tip on digital electrons **race times**

•Think about this circuit, if you changed the inputs from 11 to 00 the outputs would not change.





#### Let's draw this out in detail





## Last tip on digital electrons **race times**



Roderick MacKenzie

MM2EMD Electromechanical devices

The University of

Nottingham



MM2EMD Electromechanical devices

- •All gates have a 'turn on' and 'turn off' time.
- •This is in effect a time it takes the gate to react to an input -  $\tau$ .



**Roderick MacKenzie** 

### Last tip on digital electrons **race times**



Roderick MacKenzie

MM2EMD Electromechanical devices

The University of

Nottingham

## Last tip on digital electrons **race times**



- •Gates take microseconds to respond.
- •This means your output can be wrong for up to a microsecond.
- •The more gates you have the longer theses effects will last for.
- •Often glitches don't matter, but if you are designing sensitive (fast) circuits, they can be really really important.



106 MM2EMD Electromechanical devices



Recap of last lecture

•Using JK flip flops to run motors

Digital design
What is digital design?
How to do it.
Where you might meat digital design
FPGAs

Race times